



# ENTAM - Test Report



Sprayer type: Trade mark: Model: Trailed field crop sprayer DUBEX Mentor 4000 l

Manufacturer: DUBEX B.V. Ohmweg 16 NL - 9503 GW Stadskanaal Netherlands

Test report: D - 2096

January 2018

#### **Assessment table**

No.	Contents	Assessment
1	Spray tank surface roughness	++
2	Spray tank over volume	++
3	Volume of total residual (here max. allowed 74 I)	+
4	Spray tank contents gauge up to 20% Filling	+++
5	Spray tank contents gauge from 20% Filling	+++
6	Agitation system	+
7	Width of nozzle bar section	+++
8	Boom height adjustment range	++
9	Accuracy of pressure gauge	++
10	Accuracy of flow meter	see no.14
11	Regulation speed	+++
12	Even transverse distribution	+++
13	Rinsing water tank	+
14	Deviation of volume/hectare adjustment device (spray compu- ter) from desired value	+
15	Repeatability of volume/hectare adjustment device (spray com- puter *	+++
16	Pressure drop between manometer and nozzle	+
17	Deviation of single nozzle output from table	++

Tab.1+2: Assessment table and assessment keys of important test results.

\*) changed requirement

No.	unit	+	++	+++	No.	unit	+	++	+++
1	μm	>70-100	30-70	<30	10	%	4-5	2-4	0-<2
2	% of al-	5-8	>8-12	>12	11	%	>7-7.5	>3-7	0-3
3	low.value	>2/3-3/3	1/3-2/3	<1/3	12	CV	>7-9	4-7	<4
						Times amount of dilutable **			
4	%	7.5-5.0	<5.0-2.5	<2.5	13	ullutable	10-12	>12-14	>14
5	%	5.0-4.0	<4.0-2.0	<2.0	14	S	>4-7	2-4	<2
6	%	>10-15	5-10	<5	15	deviation %	>4-6	2-4	<2
7	m	4.5-6	>3-4.5	3 or less	16	%	>7-10	3-7	<3
8	m	1-1.5	>1.5-2.0	>2.0	17	%	>7-10	3-7	<3
9	bar	>0.10-0.20	>0.05-0.10	0.00-0.05					

\*\*) only in horizontal position = +

Free download of the test under: www.ENTAM.net or www.julius-kuehn.de





Dimensions and weights :

total length:	6300 mm
height:	3300 mm
width:	2700 mm
unloaded weight:	3250 kg

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Fig.2: View of the right sprayer side with equipment box.

The framework of the sprayer is made of steel profiles with the tank situated on the top. The suspended axle has a track width of 2.0 m. It is designed for a road speed of 40 km/h.

The spray tank with a nominal volume of 4000 I is made of polythene. He keeps an over volume of 8.7 % to hold back foam. The pressure agitation system has his own pump (Bertolini "Poly 2210 VD") and is designed as a back-

flow system. The clean water tank for rinsing and diluting holds a volume of 393 I. The hand wash tank for the operator has a volume of 16.4 l. The boom is made from welded steel tubes. It can be adjusted in height indefinitely between 500 mm and 2500 mm with a vertical lift system. The pendulum range of the boom is +/- 11° and the slope compensation can compensate between +/-15 %. The outer 3 m segment of the boom works as obstacle give away.



Fig.3: Sprayer underside with axle.

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#### **Description of sprayer**



Fig.4: Rear view with boom and boom lift for the lateral folding boom.

The outer 4.5 m boom segments are equipped with additional bars to protect the nozzles in case of ground contact of the boom. The boom can be equipped with ultrasonic sensors for detecting and automatically keeping the adjusted boom height over ground. In the tested version the boom was outfitted with spotlights to make the spray visible for controlling.

Via pneumatic single nozzle switching the nozzles can be grouped together to individual spray sections (before delivery), controlled by the spray computer. With the used spray computer (Müller Touch ME1200) it is possible to adjust and control all important spraying and boom movement functions from the

driver's place. All necessary controls and connections for filling, agitation and inner tank cleaning are centralized on the left sprayer side. In case of blockage, the central suction filter is easy to reach. The central pressure filter will be flushed automatically.



Fig.5: Ccontrol center on the left sprayer side.

## **Description of sprayer**



Fig.6: Stainless steel induction bowl with contents indicator and rotating nozzle for can rinsing.

The stainless steel induction bowl (left sprayer side) offers a circular manifold under the rim for flushing in chemicals. For the inner cleaning of empty chemical containers an additional rotating nozzle is present in the bowl. It is switched on by pushing an empty can over the rotating nozzle. The opening of the bowl is round about 90 cm above ground and therefore easy to reach.

## **Result table**

tested assembly			result (measured)			
spray tank	oray tank over volume			8.7 %		* min. 5 %
	contents gauge		graduation marks	electronical	display	* max. 100 l
			deviation	-2.2 %	, 0	* max. 7.5 % between 400l and 800 l.
				1.8 %	)	* max. 5 % bet- ween 800 l and 4000 l
	surface roughnes	S		0.039 m	ım	* max 0.1 mm
rinsing tank	volume			393 I		*10 times dilu- table volume, in horiz. position
	rinsing and dilution possible?			yes	yes	
	Cleaning performance (main tank) (concentration after cleaning)			2791		Min.factor 400 of concentration before cleaning
can rinsing e	equipment	rinsing efficiency		<0.01 %		* max. 0.01 % of can contents
manometer	graduation marks			0.1 ba	r	* max. 0.2 bar
	deviation			-0.1 ba	ar	* max. 0.2 bar
agitation deviation from events of the second system		en concentration		-12,5 %		*max. 15 %
residual in l		dilutable		68.8 l		* max. 74 l
		non dilutable		11		
spray boom	height adjustmer	nt rang	ge from - to	500 mm - 2500 mm		
	nozzle ground co	ntact	protection	yes		
	pressure loss between manor and nozzle at 4 bar pressure		manometer essure	-10 %		* max. 10 %
	nozzle dripping a	fter s	witch off	0 ml		* max. 2 ml
	single nozzle flow	v rate				
		pres- sure (bar)	flow rate (I/ min)	max. deviation from table in % *(max. 10 %)	max. dev in %	iation from mean *(max. 5 %)
		3.0	1.95	-4.1		4.2
	transverse distribution					
	pressure (bar) distance (cr		distance (cm)	coefficient of variation (%) *(max. 9 %)		
		1.5	50		2.7	
		3.0	40		3.5	
		4.0	50		2.2	
	Measured wit	h :		Lechler IDK	T 120-05	

Tab.3: Result table

\* limit

#### **Result table**

volume/hectare adjustment device					
repeatability of adjustment					
	adjusted flow rate in l/ha	deviation from desi- red value % **	deviation from desi- red value % **		
		ascending applicati- on rate	descending applicati- on rate		
	238	-0.5	-0.2		
	340	-0.9	-0.9		
	442	-1.3	-1		
procedure	procedure		regulation speed: deviation to adjusted value after 7 s		
	switching on / off	1.8 s***	after 7 s		
	switching of single sections	1.6 s***	after 7 s		
procedure		reaching steady sta varing conditior	ate after ns (s)		
	change of driving speed by changing gears		steady state mean deviation		
	1.5 m/s to 2.0 m/s	5.1 s	*		
	2.0 m/s to 2.5 m/s	6.4 s	*		
	2.5 m/s to 2.0 m/s	5.5 s	*		
	2.0 m/s to 1.5 m/s	6.9 s	*		

Tab.4: Result table 2.

\* limit: < 10 % after 7 s

\*\* limit: m,ax. 6 %

\*\*\*steady state reached

#### Explanation on testing:

Testing takes place according to the Technical Instructions for ENTAM-Tests of Field Crop Sprayers (Rel.5). This procedure was developed by the competent testing authorities of the European countries participating in ENTAM and is based on the standard EN ISO 16119. This test is only a technical performance test which takes place without an accompanying field test. The test results apply only to the tested appurtenances of the sprayer. Statements on the behaviour of the sprayer with different appurtenances cannot be derived from these results.

## Responsibility and recognition



Performing competent authority: Julius Kühn-Institute (Germany) Institute for Application Techniques in Plant Protection Messeweg 11-12 D-38104 Braunschweig

### This test is recognized by the ENTAM members:



GÖDÖLLŐ

at	HBLFA Francisco Josephinum BLT Wieselburg (Austria)	002/2018
	<b>CMA</b> Generalitat de Catalunya Centre de Mecanització Agrària (CMA) (Spain)	EPH 02/18
	<b>ENAMA</b> Ente Nazionale per la Meccanizzazione (Italy)	ENTAM "Rapporto di Agricola prova prestazionale" 02/2018
Ì	<b>HIAE</b> (MGI) Hungarian Institute of Agricultural Engineering (Hungary)	D-168/2018
	<b>IRSTEA</b> - National Research Institute of Sience and Technology for Enviroment and Agriculture (France) (formerly CEMAGREF)	IRSTEA/CEMAGREF/ENTAM/ 18/002
	<b>PIMR</b> - Przemyslowy Instytut Maszyn Rolniczych Industrial Institute of Agricultural Engineering (Poland)	PIMR-183/ENTAM/18